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Optimal Multicast Service Chain Control: Packet Processing, Routing, Duplication

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- Increasing demand for computational resource
 - Augmented reality, telepresence, industrial automation
- Limited local computational resource at UE
 - Tendency: light weight, portable devices
 - Restricted processing capability, battery
- Solution: offloading computing tasks to the cloud
 - Better delay and cost performance





- Distributed cloud network
 - Make it easier for the UEs to access the computational resource
 - Traditional processing network: separation of network & processing center
 - Distributed cloud network: deploy the computational resource in a more widespread manner
- NFV & SDN-enabled Next-Gen Cloud
 - Make it more flexible for the cloud to process the data-stream
 - Augmented information service: computing task → service function chain
 - Each individual function can be implemented separately (at different network locations)



- Multicast flow is an increasingly dominant component of the network traffic
 - Applications with multiple destinations
 - Multi-user conferencing
 - Coordinated decision making/content distribution within multi-agent systems
 - Intelligent transportation system, smart factory











- Existing Studies
 - Heuristic algorithms
 - Unicast approach: treat multicast flow as several individual unicast flows



- Throughput-optimal, least cost multicast routing
 - Few results (centralized control requiring global information)





- Cloud network model
 - Node: data-centers
 - Computation capacity C_i , associated cost e_i
 - Edge: transmission link
 - Transmission capacity C_{ij} , associated cost e_{ij}



- Service model
 - Service function chain: a chain of ordered functions
 - Two parameters: scaling factor $\xi_{\phi}^{(m)}$, workload $r_{\phi}^{(m)}$
 - Destination set \mathcal{D} (multicast)
 - It becomes a singleton $\mathcal{D} = \{d\}$ for unicast flow
 - I.I.D. requests from each client
 - $a_i(t)$: the instantaneous arrival
 - λ_i : mean arrival rate





- Duplication operation
 - Current destination set
 - Keep track of the destination set of each copy of a content
 - Duplication status vector
 - Binary vector
 - Example: q = (0, 1), the service has two destinations, and the packet is assigned the second destination





- Duplication operation (assumptions)
 - The coverage constraint

$$\begin{array}{ll} q & \leq s + r \\ \text{original} \\ \text{packet} \end{array} \quad \text{two copies} \end{array}$$

• *Efficient* duplication: destination sets of the copies do not overlap

$$q=s+r$$

- 2-duplication



Policy Space

- Policy space
 - Decision variable: the flow variables $f(t) = \{f_{i,pr}^{(q)}(t), f_{ij}^{(q)}(t)\}$
 - Constraints
 - 1. Non-negativity $f(t) \succeq 0$
 - 2. Capability constraint

$$\tilde{f}_i(t) = \sum_q r_{\phi}^{(m)} f_{i,\text{pr}}^{(q)}(t) \le C_i, \quad f_{ij}(t) = \sum_q f_{ij}^{(q)}(t) \le C_{ij}$$

3. Generalized flow conservation law



Policy Space



- Policy space
 - Decision variable
 - Constraints
 - 3. Generalized flow conservation law (coverage constraint)



Policy Space



- Policy space
 - Decision variable
 - Constraints
 - Generalized flow conservation law (efficient duplication)(it does not reduce throughput, but can save cost and network traffic)

$$\sum_{\{q:q_k=1\}} \left[f_{\to i}^{(q)} + \lambda_i^{(q)} \right] = \sum_{\{q:q_k=1\}} f_{i\to}^{(q)}$$



Queuing System



- Queuing system
 - Queues $\boldsymbol{Q}(t) = \left[Q_i^{(q)}(t)\right]$
 - The queue commodity (c, q) at node i on time slot t
 - Flow variables $\boldsymbol{x}(t) = \left[x_{ij}^{(q,s)}(t) \right]$
 - The planned number of commodity q packets, such that they are duplicated into two copies with status s and q s, with the first copy sent from node i to j, and the second copy reloaded
 - This variable specifies both the duplication and the routing decisions



Queuing System

- Queuing system
 - An example
 - Queuing dynamics
 - Intermediate nodes



$$Q_i^{(q)}(t+1) \le \left[Q_i^{(q)}(t) - \sum_{s \in 2^q} \mu_{i \to}^{(q,s)}(t)\right]^+ + \mu_{\to i}^{(q)}(t) + a_i^{(q)}(t)$$

$$\begin{split} \mu_{i \to}^{(q,s)}(t) &= x_{i,\mathrm{pr}}^{(q,s)}(t) + \sum_{j \in \delta_i^+} x_{ij}^{(q,s)}(t) \\ \mu_{\to i}^{(q)}(t) &= \sum_{s \in 2^{\bar{q}}} \left[x_{\mathrm{pr},i}^{(q+s,q)}(t) + \sum_{j \in \delta_i^-} x_{ji}^{(q+s,q)}(t) \right] + \sum_{s \in 2^{\bar{q}}} \mu_{i \to}^{(q+s,s)}(t) \end{split}$$



Problem Formulation



$$\min_{\boldsymbol{x}(t)} \quad \overline{\{\mathbb{E}\{h(t)\}\}} \qquad h(t) = \sum_{i \in \mathcal{V}} e_i \tilde{f}_i(t) + \sum_{(i,j) \in \mathcal{E}} e_{ij} f_{ij}(t)$$

s.t. stabilize $\boldsymbol{Q}(t)$

$$\begin{aligned} x_{\mathrm{pr},i}^{(\phi,m+1,\mathcal{D},q,s)}(t) &= \xi_{\phi}^{(m)} x_{i,\mathrm{pr}}^{(\phi,m,\mathcal{D},q,s)}(t) \\ \tilde{x}_{i}(t) &\triangleq \sum_{(c,q,s)} r_{\phi}^{(m)} x_{i,\mathrm{pr}}^{(c,q,s)}(t) \leq C_{i} \quad \forall i \in \mathcal{V} \\ x_{ij}(t) &\triangleq \sum_{(c,q,s)} x_{ij}^{(c,q,s)}(t) \leq C_{ij} \quad \forall (i,j) \in \mathcal{E} \\ \boldsymbol{x}(t) \succeq 0 \end{aligned}$$



Proposed Algorithm



- Based on Lyapunov Drift-plus-Penalty (LDP) approach
 - Goal: to minimize LDP given by

$$\begin{split} \Delta(t) + Vh(t) \\ &\leq B - \sum_{i \in \mathcal{V}} \sum_{(c,q,s)} w_i^{(c,q,s)} x_{i,\mathrm{pr}}^{(c,q,s)}(t) - \sum_{(i,j) \in \mathcal{E}} \sum_{(c,q,s)} w_{ij}^{(c,q,s)} x_{ij}^{(c,q,s)}(t) \\ w_i^{(c,q,s)} &= \frac{Q_i^{(c,q)}(t) - Q_i^{(c,q-s)}(t) - \xi_{\phi}^{(m)} Q_i^{(c',s)}(t)}{r_{\phi}^{(m)}} - Ve_i \\ w_{ij}^{(c,q,s)} &= Q_i^{(c,q)}(t) - Q_i^{(c,q-s)}(t) - Q_j^{(c,s)}(t) - Ve_{ij} \end{split}$$



Proposed Algorithm



- Algorithm
 - 1) calculate the weight for each tuple (c, q, s);
 - 2) find the tuple (q, s, c) with the largest weight, i.e.,

$$(q, s, c)^{\star} = \underset{(q, s, c)}{\operatorname{arg\,max}} w_i^{(q, s, c)} \text{ (or } w_{ij}^{(q, s, c)});$$

3) the optimal flow assignment is given by

$$\begin{aligned} x_{i,\mathrm{pr}}^{(q,s,c)}(t) &= \frac{C_i}{r_{\phi^{\star}}^{(m^{\star})}} \mathbb{I}\left\{ (q,s,c) == (q,s,c)^{\star}, w_{ij}^{(q,s,c)^{\star}}(t) > 0 \right\} \\ x_{ij}^{(q,s,c)}(t) &= C_{ij} \mathbb{I}\left\{ (q,s,c) == (q,s,c)^{\star}, w_{ij}^{(q,s,c)^{\star}}(t) > 0 \right\} \end{aligned}$$

where $\mathbb{I}\{\cdot\}$ denotes the indicator function, which equals to 1 only when the two conditions are both satisfied.



Performance Analysis



• Delay-cost trade-off

Theorem 2: For any arrival vector λ that is in the interior of the capacity region, the queue backlog and the cost achieved by the proposed algorithm satisfy

$$\overline{\{\mathbb{E}\{\|\boldsymbol{Q}(t)\|_1\}\}} \leq \frac{B}{\epsilon} + \left[\frac{h^*(\boldsymbol{\lambda} + \epsilon \mathbf{1}) - h^*(\boldsymbol{\lambda})}{\epsilon}\right] V \sim \mathcal{O}(V)$$
$$\overline{\{\mathbb{E}\{h(t)\}\}} \leq h^*(\boldsymbol{\lambda}) + \frac{B}{V} \sim \mathcal{O}(1/V)$$

for any $\epsilon > 0$ such that $\lambda + \epsilon \mathbf{1} \in \Lambda$.

- The average delay is proportional to $\overline{\{\mathbb{E}\{\|\boldsymbol{Q}(t)\|_1\}\}} \sim \mathcal{O}(V)$



Numerical Experiments

- Configuration
 - Network topology (Abilene network)
 - Available resource & cost



- The computational resource is 20 CPUs at any node, with cost 0.5 /CPU
- The transmission resource is 10 Gbps for any link, with a cost of 1 /Gb
- Provided service
 - Two AgI services, each including two functions with parameter:

$$\phi_1: \ \xi_1^{(1)} = 1, \ \xi_1^{(2)} = 2; \ 1/r_1^{(1)} = 300, \ 1/r_1^{(2)} = 400$$

 $\phi_2: \ \xi_2^{(1)} = 1/3, \ \xi_2^{(2)} = 1/2; \ 1/r_2^{(1)} = 200, \ 1/r_2^{(2)} = 100$



Numerical Experiments



- Network capacity region
 - Different V value leads to the same capacity region
 - Achieve 2 × the capacity region of unicast approach
 - Since there are 2 destinations





Numerical Experiments



- Tradeoff controlled by V parameter
 - [O(V), O(1/V)] tradeoff
 between queue backlog and
 the achieved cost
 - Achieve 1/2 × the cost of unicast approach
 - Since there are 2 destinations





Conclusions



- The delivery of multicast network flow can be optimized by exploiting the reuse gain
- Efficient duplication can 1) ensure information delivery to all destinations, and 2) save the network resource
- The proposed approach can support the entire capacity region and achieve near-optimal cost performance



Acknowledgement



- Thanks for joining in the talk!
- Please contact yangcai@usc.edu if you have any questions, comments
- The most recent results on this topic (which deals with mixed-cast flows) are under preparation for submission to IEEE Trans. Comm.



Queuing System



- Queuing system
 - Queuing dynamics
 - Destination $i = d_k$

$$Q_i^{(c,q)}(t+1) \le \begin{cases} 0 & q_k = 1\\ R + \mu_{\to i}^{(c,q+b_k)}(t) + a_i^{(c,q+b_k)}(t) & q_k = 0 \end{cases}$$

• Example: what happens if a (1, 1) packets arrives at d_1

(1, 1) (1, 0): depart the network since it is at d_1 (1, 1) (0, 1): join the queue for (0, 1) at d_1





- Request model
 - Destination set \mathcal{D} (multicast)
 - It becomes a singleton $\mathcal{D} = \{d\}$ for unicast flow
 - Commodity $c = (\mathcal{D}, \phi, m)$
 - (destination set, request service, current stage in the service function chain)
 - I.I.D. requests from each client
 - $a_i^{(c,q)}(t)$: the instantaneous arrival
 - $\lambda_i^{(c,q)}$: mean arrival rate

